

- + ○ Machine Learning Based Control System Design for BSM1 Wastewater Treatment Plant

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General overview of the BSM1 plant

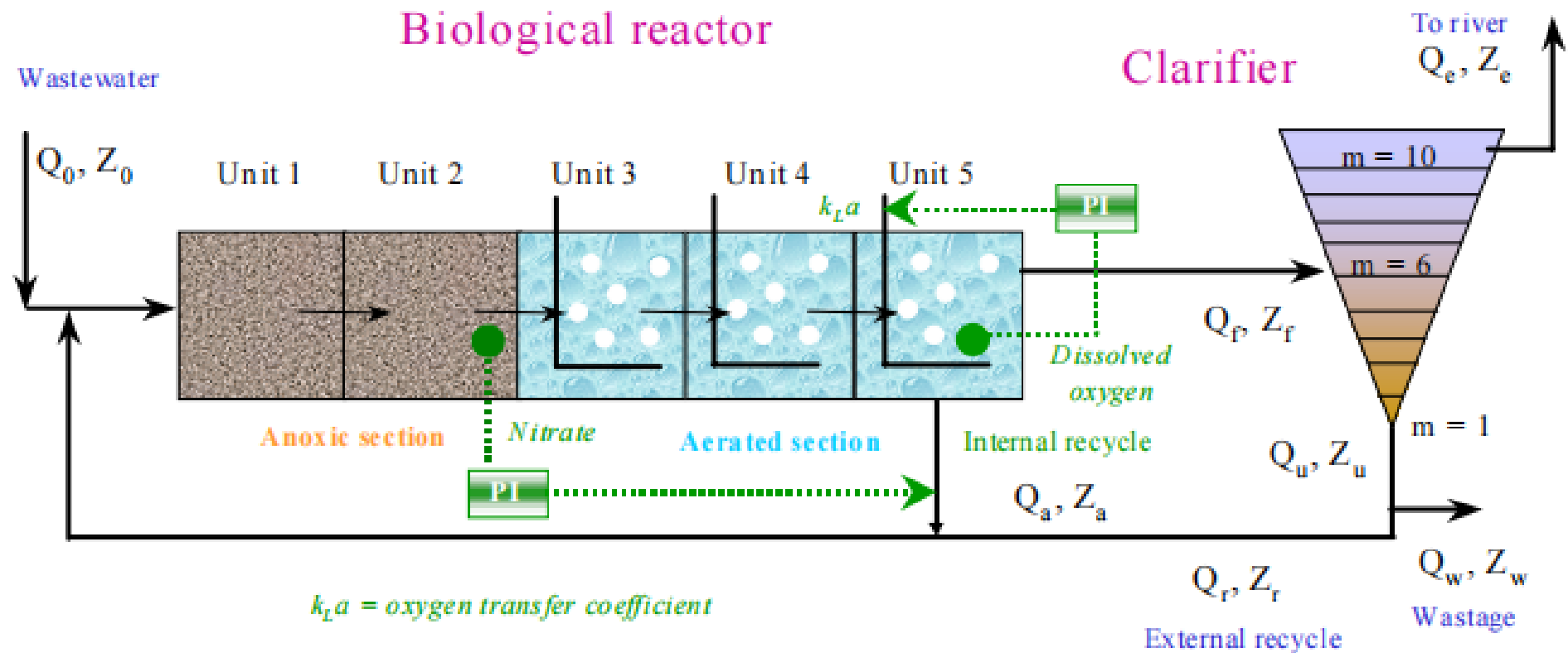
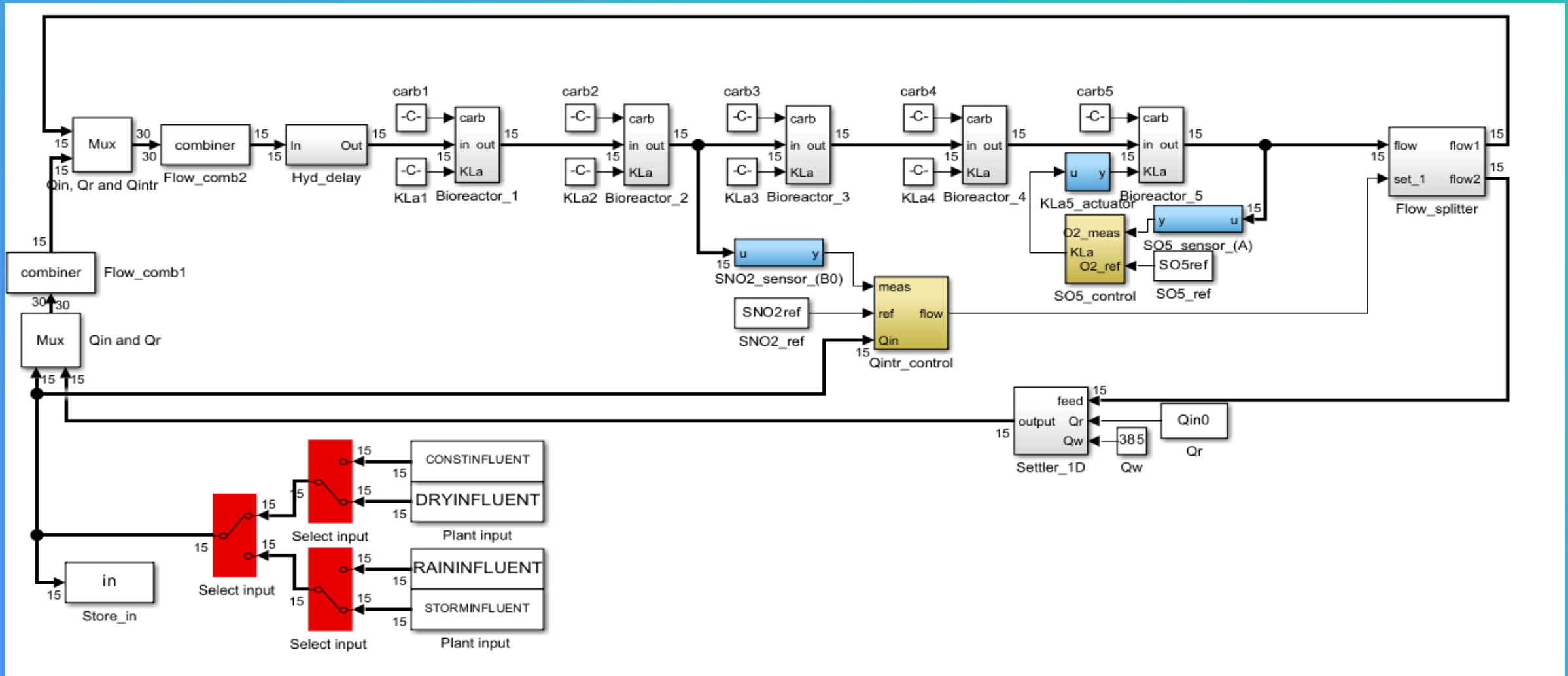


Figure 1: General overview of the BSM1 plant

BSM1 MATLAB SIMULINK OUTLINE



| Variable | Value |
|--------------------|-----------------------------|
| N_{tot} | $<18 \text{ g N.m}^{-3}$ |
| COD_{tot} | $<100 \text{ g COD.m}^{-3}$ |
| S_{NH} | $<4 \text{ g N.m}^{-3}$ |
| TSS | $<30 \text{ g SS.m}^{-3}$ |
| BOD_5 | $<10 \text{ g BOD.m}^{-3}$ |

Effluent quality limits

Effluent quality violations

- Problem: Three (Dry, Rain, Storm) scenarios have violations on effluent quality
- Goal: Improve the effluent quality (lower the violations) by using better control system design

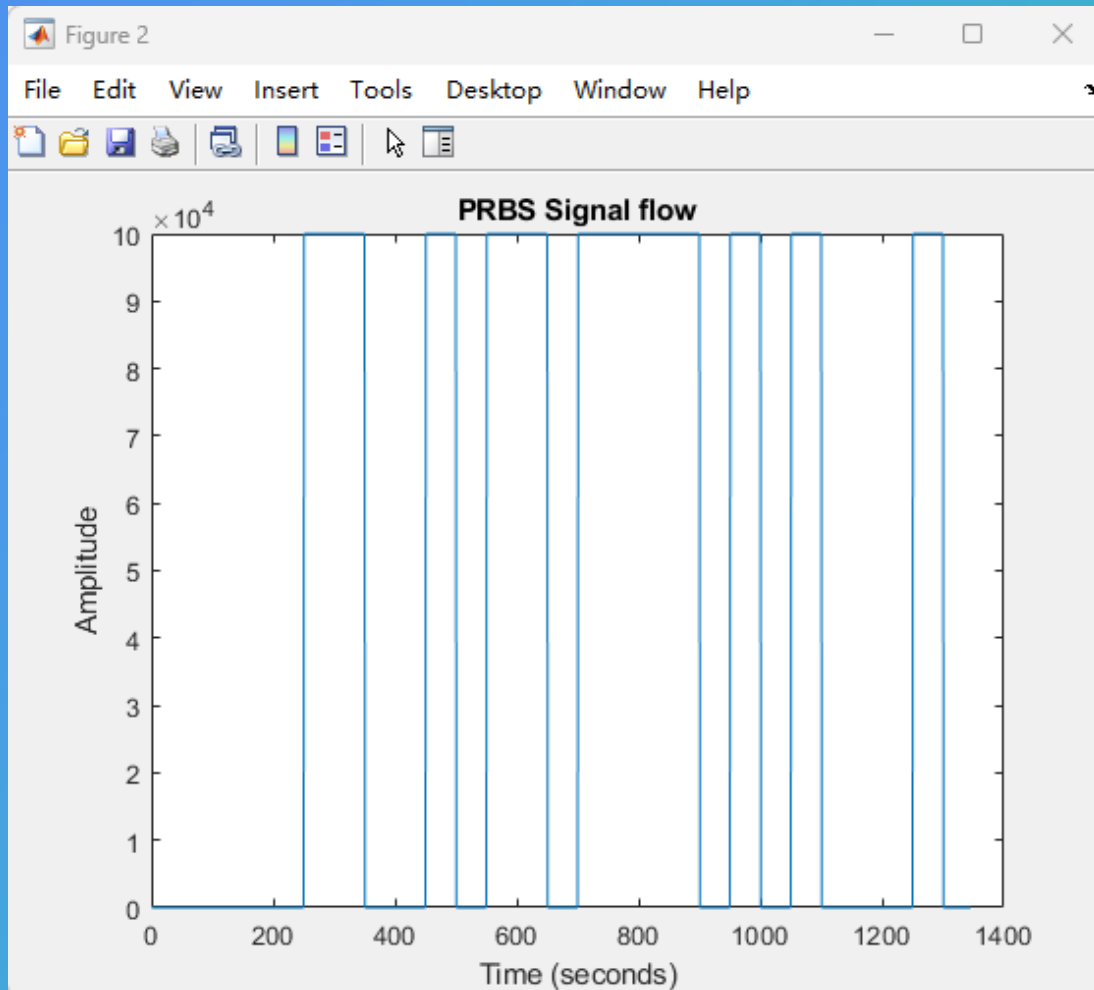
Effluent violations

 95% percentile for effluent SNH (Ammonia95) = 10.6066 g N/m³
 95% percentile for effluent TN (TN95) = 20.1673 g N/m³
 95% percentile for effluent TSS (TSS95) = 20.9932 g SS/m³

The maximum effluent total nitrogen level (18 mg N/l) was violated during 2.1979 days, i.e. 31.3988% of the operating time.
 The limit was violated at 9 different occasions.

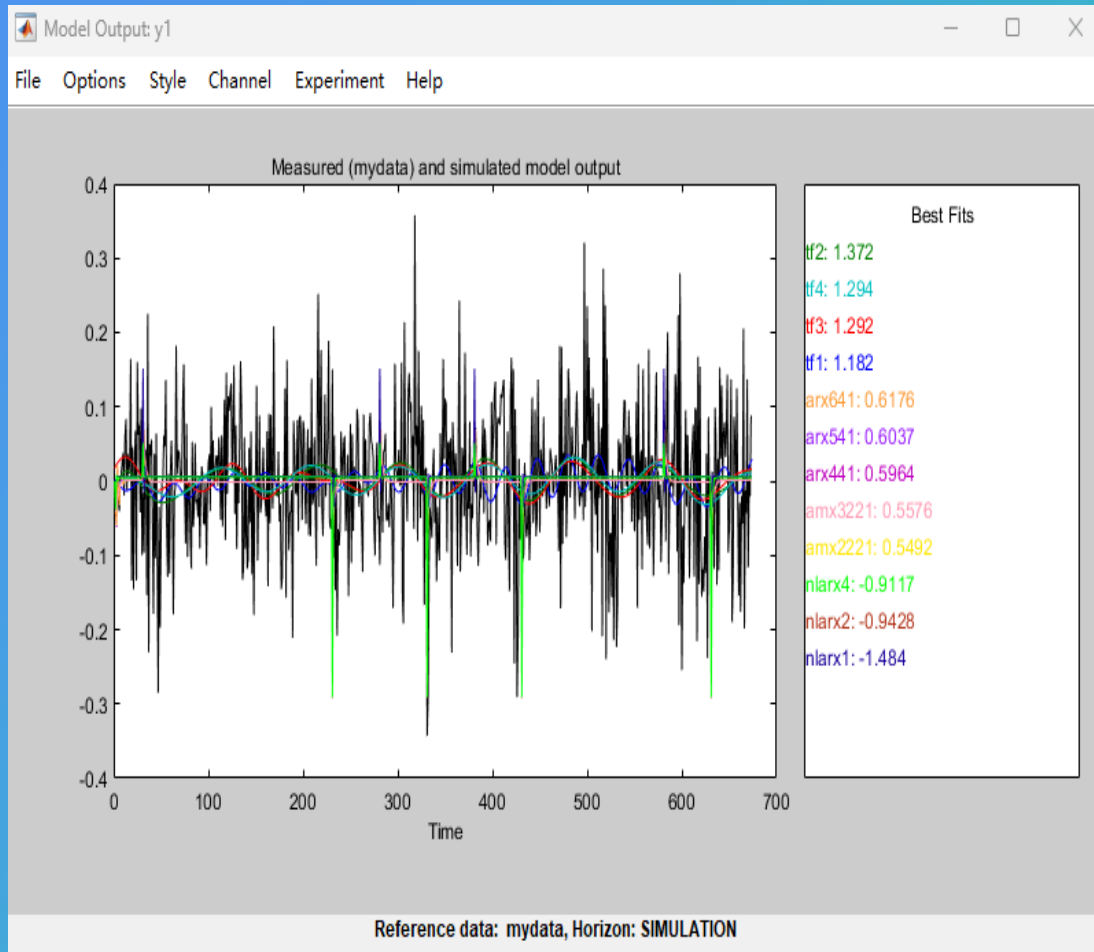
The maximum effluent ammonia nitrogen level (4 mg N/l) was violated during 4.6667 days, i.e. 66.6667% of the operating time.
 The limit was violated at 8 different occasions.

Data Driven Modeling using PRBS signal



- **Pseudorandom Binary Sequence (PRBS)**
 - Binary Sequence (two values)
 - Random
 - Commonly using for testing and evaluating systems

Dryinfluent (SO5)



Bad fitting with traditional data driven methods

- Input:
 - Internal Recycle Flow Rate
 - KLA5 (oxygen transfer coefficient)
- Output:
 - NO₃-N(Nitrate) in the Second Anoxic Compartment (SNO2)
 - Dissolved Oxygen in the Last Aerated Compartment (SO5)
- Best fit range: 0-3 %

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Machine Learning Based Control

- We model the control system rather than modelling the process
- Methodology
 - Generate 15 rain and 15 storm scenarios
 - Generate random combinations of PI parameters and setpoints
 - Run BSM1 simulation and collect the data
 - Build the regression model
 - Use the regression model to search the optimal combinations of PI parameters and setpoints

Generating Scenarios



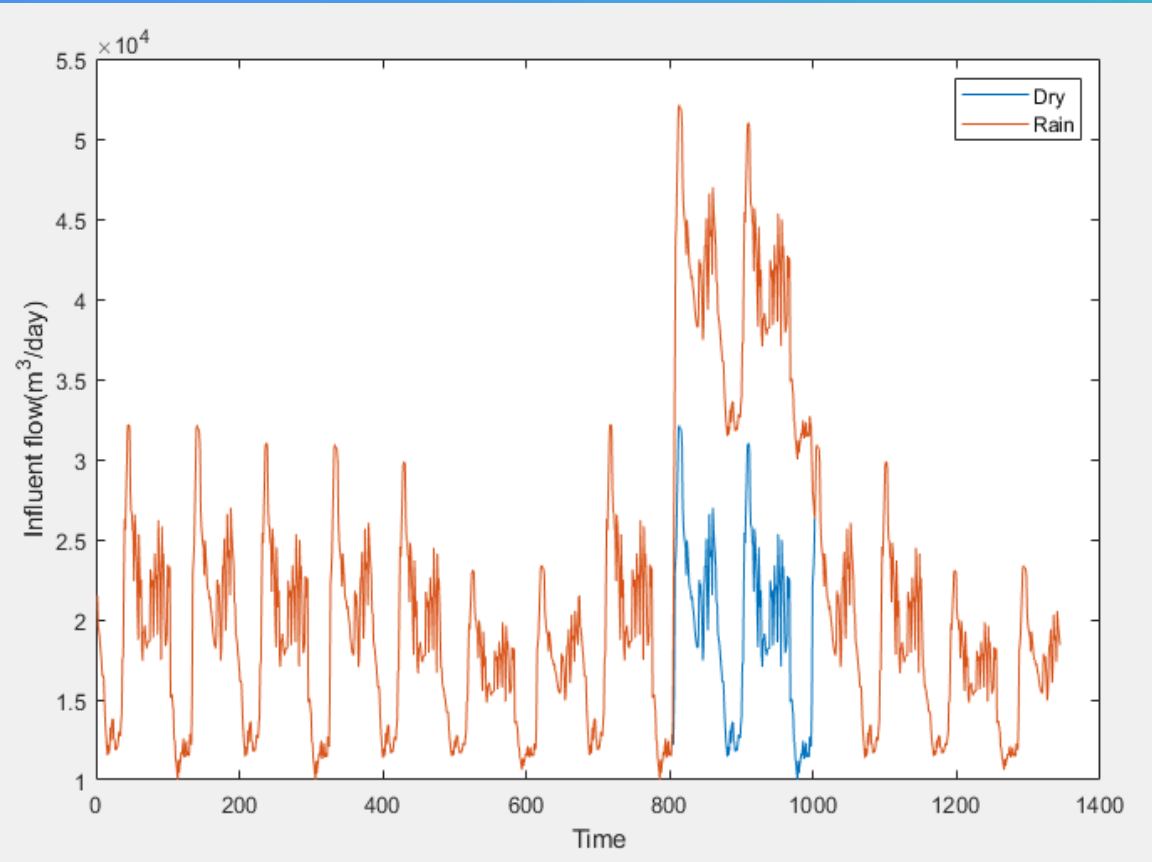
Three dynamic influent (Dry, Rain, and Storm)

Rain influent: Dry influent + 1 rain event

Storm influent: Dry influent + 1 storm event + 1 rain event

Following the pattern, we modify when the event starts, how long it lasts, and the magnitude of the peak and trough.

Generating Scenarios



- Pre-control phase: 0-7s (first week)
- Control action: 7s - 14s (second week)
- Influent soluble concentrations (S_s , S_{NH} , S_{ND} , S_I)
- Influent particulate concentrations (X_I , X_{BH} , X_{BA} , X_S , X_{ND})
- Methodology of generating rain scenarios
 - Modify the influent flow
 - Modify the load concentrations follow the dilution calculation

Simulation and data collection



1

Generate random combinations of PI parameters and setpoints

2

Run simulations of each combination of PI parameters and setpoints (total 9 variables) with 30 scenarios

3

Collect the jointed violation time of each simulation

4

Take the average violation time of 30 scenarios with each combination of PI parameters and setpoints

Machine Learning Based Regression model

Predictors: combination of PI parameters and setpoints (total 9 variables)

Response: the average violation time

Using the **machine learning regression** model, we can estimate the relationship between Predictors and Response

Once we built the model, we can use it to make prediction of new predictors

Modelling result



Violation time **default PI**
performance (no
sensornoise)

Dry: 68.6429%
Rain: 73.3631%
Storm:
71.7262%

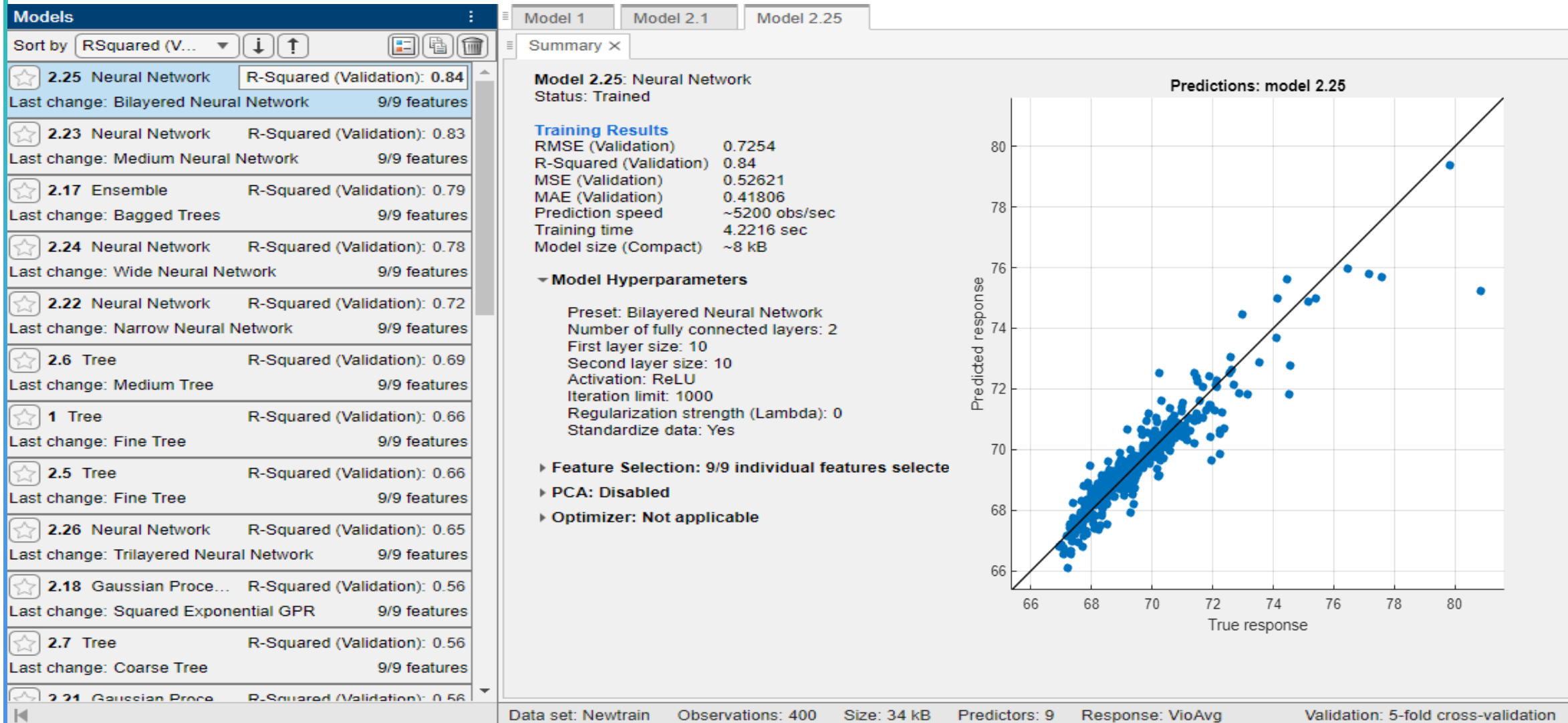


Simulation result

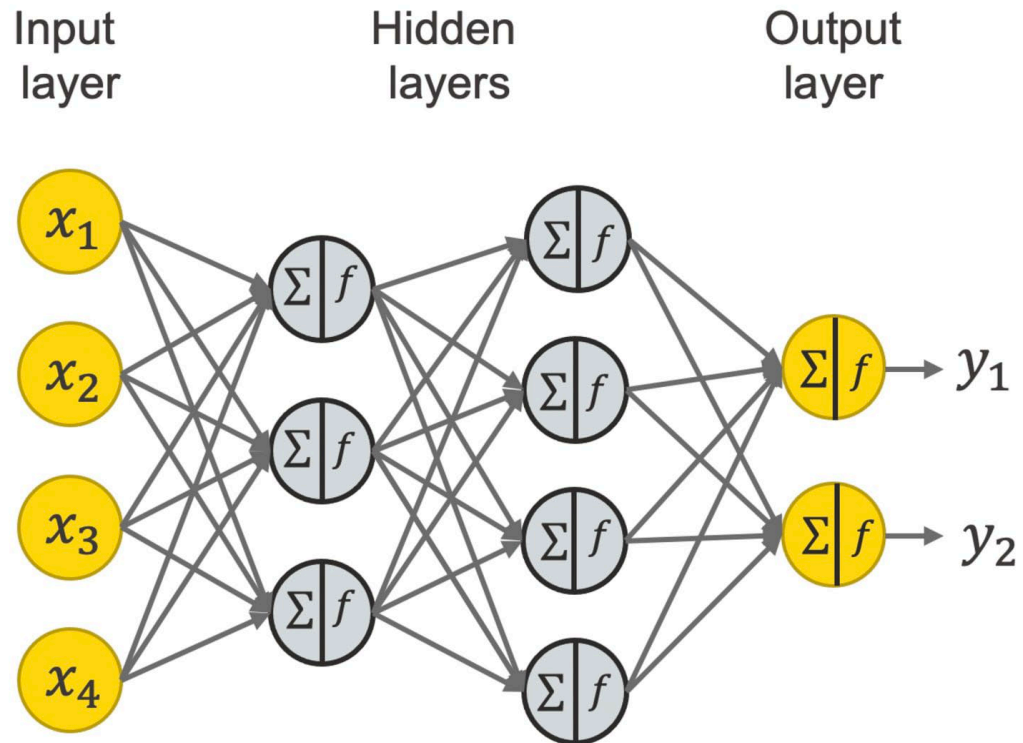
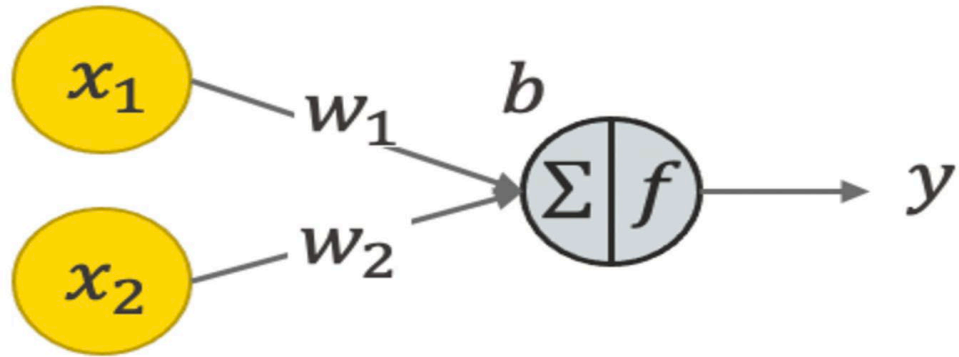
400 sets data
Range:
66.9296% to
80.8681%



Machine Learning Based Modelling result



Neural network



- Input layer: Predictors (9 variables)
 - First layer: 10 neurons
 - Second layer: 10 neurons
 - Output layer: Response
 - Each neuron has its own set of weights and a bias
 - Each neuron output can be defined by 2 steps
 - $x_1 * w_1 + x_2 * w_2 + b$
 - An activation function (ReLU)
- $$\text{ReLU}(x) = \begin{cases} x, & x > 0 \\ 0, & x \leq 0 \end{cases}$$
- Use the previous layer values to calculate its output

Continuing work

Generate

Generate more combination of PI parameters and setpoints (total 9 variables)

Use

Use the regression model to make predictions

Search

Search the optimal combination with the lowest value of response

References

- (1) Alex, Jens & Benedetti, Lorenzo & Copp, Jb & Gernaey, Krist & Jeppsson, Ulf & Nopens, Ingmar & Pons, Marie-Noelle & Rieger, Leiv & Rosen, Christian & Steyer, J-P. (2008). Benchmark Simulation Model no. 1 (BSM1). Report by the IWA Taskgroup on Benchmarking of Control Strategies for WWTPs.
- (2) Vanhooren H., Nguyen K. (1996) Development of a simulation protocol for evaluation of respirometry-based control strategies. Report University of Gent and University of Ottawa.
- (3) Melcher, K. (n.d.). *A friendly introduction to [deep] neural networks*. KNIME. <https://www.knime.com/blog/a-friendly-introduction-to-deep-neural-networks>